



Self-consistent collective path and inertial mass in nuclear fusion/fission reactions

Kai Wen

(University of Tsukuba)

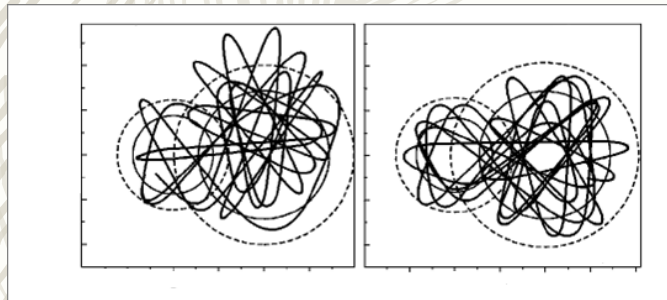
Collaborator: Takashi Nakatsukasa

(University of Tsukuba)

To study the **nuclear large amplitude collective motion**

Microscopic description

- Time dependent density functional theory(TDHF);
- Quantum molecular dynamics (QMD);
-



$$\Psi(t) = \frac{1}{\sqrt{A!}} \det\{\psi_1(t)\psi_2(t)\cdots\psi_A(t)\},$$
$$i\hbar \frac{\partial}{\partial t} \psi_j(r) = h(\rho)\psi_j(t).$$

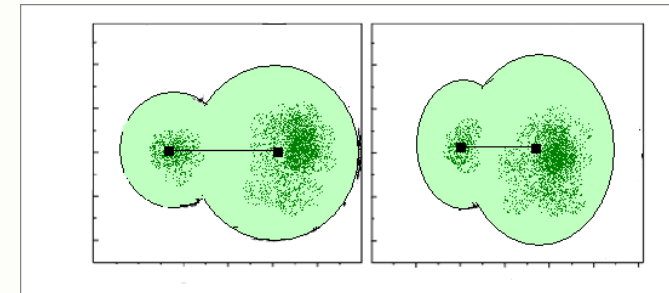
P. Bonche et al., Phys. Rev. C 13, 1226 (1976).

J. Aichelin, Phys. Rep. 202, 233 (1991).

... ..

Collective dynamics

- Adiabatic Self-consistent Collective Coordinate (ASCC) method
 - Define the collective coordinates;
 - Construct the collective Hamiltonian



$$H(p, q) = \frac{p^2}{2M} + V(q),$$

- M. Matsuo, T. Nakatsukasa, and K. Matsuyanagi, Prog. Theor. Phys. **103**, 959 (2000)
- N. Hinohara, T. Nakatsukasa, M. Matsuo, and K. Matsuyanagi, Prog. Theor. Phys. **117**, 451 (2007).



Content:

The Adiabatic Self-consistent Collective Coordinate (ASCC) Method

The inertial mass for ${}^8\text{Be} \leftrightarrow \alpha + \alpha$.

- CHF+LRPA mass
- ASCC mass
- Cranking mass and ATDHF

The collective motion paths.

Summary

The ASCC Method

Purpose:

Determine a collective motion path parameterized by $\psi(p, q)$. The evolution of p and q obey the classical Hamilton's equation with Hamiltonian

$$H(p, q) = \frac{p^2}{2M} + V(q),$$

Assumption:

The adiabatic limit: collective momentum p is assumed to be small:

$$|\psi(p, q)\rangle = (1 + i\hat{Q}p - \frac{1}{2}\hat{Q}^2p^2)|\psi(q)\rangle,$$

Starting point:

The Time dependent variational principle:

$$\delta \langle \psi(q, p) | i \frac{\partial}{\partial t} - \hat{H} | \psi(q, p) \rangle = 0,$$

The ASCC equations

$$\delta \langle \psi(q) | \hat{H}_{\text{mv}}(q) | \psi(q) \rangle = 0$$

(1): moving mean field equation

$$\begin{aligned} \delta \langle \psi(q) | [\hat{H}_{\text{mv}}(q), \frac{1}{i} \hat{P}(q)] - \frac{\partial^2 V}{\partial q^2} \hat{Q}(q) | \psi(q) \rangle &= 0, \\ \delta \langle \psi(q) | [\hat{H}_{\text{mv}}(q), i \hat{Q}(q)] - \frac{1}{M(q)} \hat{P}(q) | \psi(q) \rangle &= 0, \end{aligned}$$

(2): moving RPA equation

with moving mean field Hamiltonian:

$$\hat{H}_{\text{mv}}(q) \equiv \hat{H} - (\partial V / \partial q) \hat{Q}(q)$$

Eqs. (2) can be transformed to a eigenvalue problem:

$$\begin{aligned} (A + B)(A - B)Q &= \omega^2 Q, \\ \frac{\partial^2 V}{\partial q^2} \frac{1}{M} &= \omega^2, \end{aligned}$$

To calculate the inertial mass

1. Pick out the one desired RPA solution (e.g. quadrupole motion):

$$\langle n | \hat{Y}_{20} | 0 \rangle \neq 0$$

From many RPA solutions:

$$\{ \varrho_1, \varrho_2, \varrho_3, \dots, \varrho_x, \dots, \varrho_n, \varrho_{n+1}, \dots \}$$

2. Transformation between collective coordinates

Collective Hamiltonian in q
(the solution of ASCC equations)

$$\begin{aligned} \hat{H}_{\text{coll}}^q &= \hat{T} + V(q), \\ \hat{T} &= \frac{1}{2M_q} \frac{\partial^2}{\partial q^2}. \end{aligned}$$

Collective Hamiltonian in R
(Defined at our convenience)

$$\begin{aligned} \hat{H}_{\text{coll}}^R &= \hat{T} + V(R), \\ \hat{T} &= -\frac{1}{2} \frac{1}{\sqrt{M(R)}} \frac{d}{dR} \frac{1}{\sqrt{M(R)}} \frac{d}{dR}. \end{aligned}$$

$$M_R = M_q \left(\frac{\partial q}{\partial R} \right)^2$$

Numerical Details

- Coordinate-space and mixed representation

$$\hat{Q} = \sum_n \sum_j Q_{nj} a_n^\dagger a_j + \text{h.c.}$$

$$\hat{Q} = \int d\vec{r} \sum_j Q_j(\vec{r}) a^\dagger(\vec{r}) a_j + \text{h.c.}$$

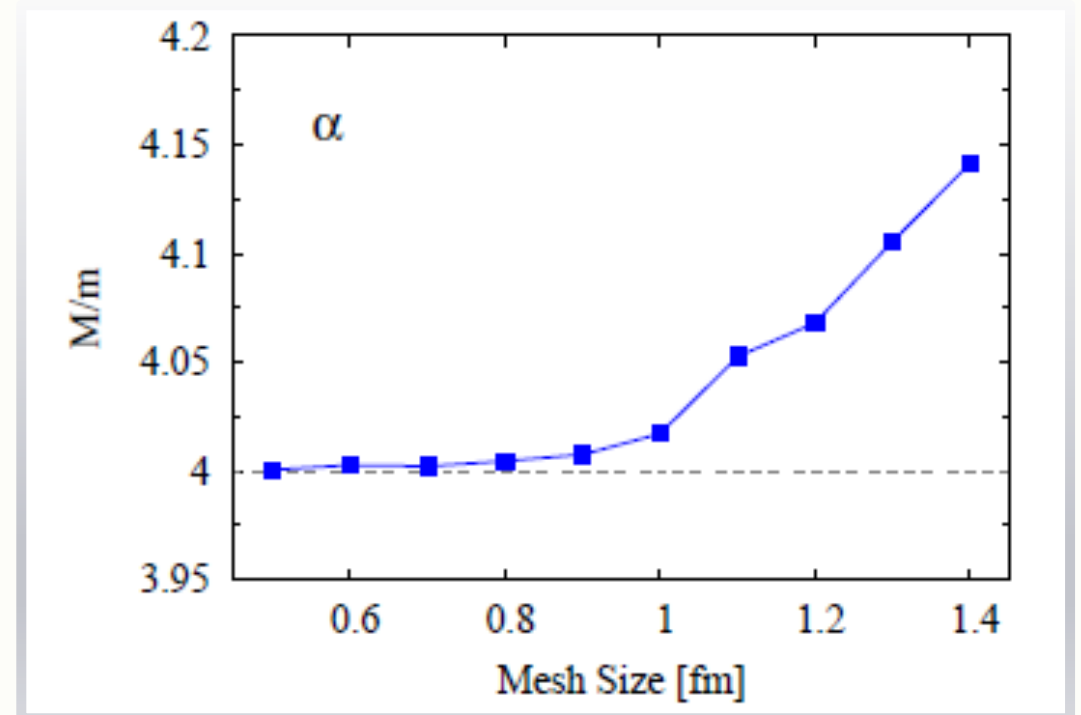
- Finite amplitude method for the moving RPA solution

P. Avogadro, T. Nakatsukasa, PRC **87**, 014331(2013)

- the BKN interaction applied

P. Bonche, S. Koonin, and J. W. Negele, Phys. Rev. C **13**, 1226 (1976).

Test calculation for the mass of one alpha particle:





Content:

❑ The Adiabatic Self-consistent Collective Coordinate (ASCC) Method

❑ The inertial mass for ${}^8\text{Be} \leftrightarrow \alpha + \alpha$.

- CHF+LRPA mass
- ASCC mass
- Cranking mass and ATDHF

❑ The ASCC collective motion paths.

❑ Summary

CHF+RPA Mass for ${}^8\text{Be} \leftrightarrow \alpha + \alpha$

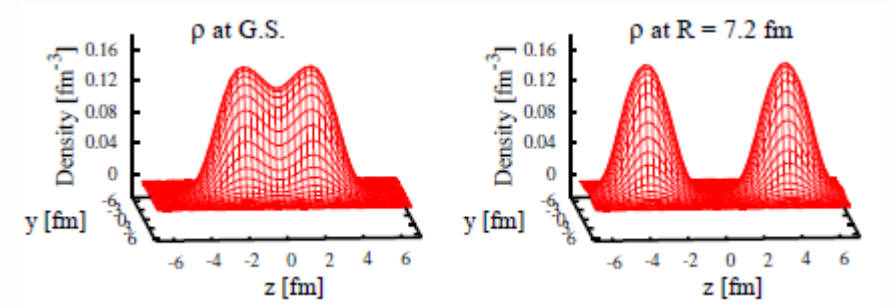
$$\delta\langle\psi(q)|[\hat{H}_{\text{mv}}(q), \frac{1}{i}\hat{P}(q)] - \frac{\partial^2 V}{\partial q^2}\hat{Q}(q)|\psi(q)\rangle = 0,$$

$$\delta\langle\psi(q)|[\hat{H}_{\text{mv}}(q), i\hat{Q}(q)] - \frac{1}{M(q)}\hat{P}(q)|\psi(q)\rangle = 0,$$

$\psi(q)$ is set to be the Constrained Hartree Fock states. We adopt the two constraints respectively:

1. *quadrupole deformation Q_{20}*
2. *Relative distance R defined as:*

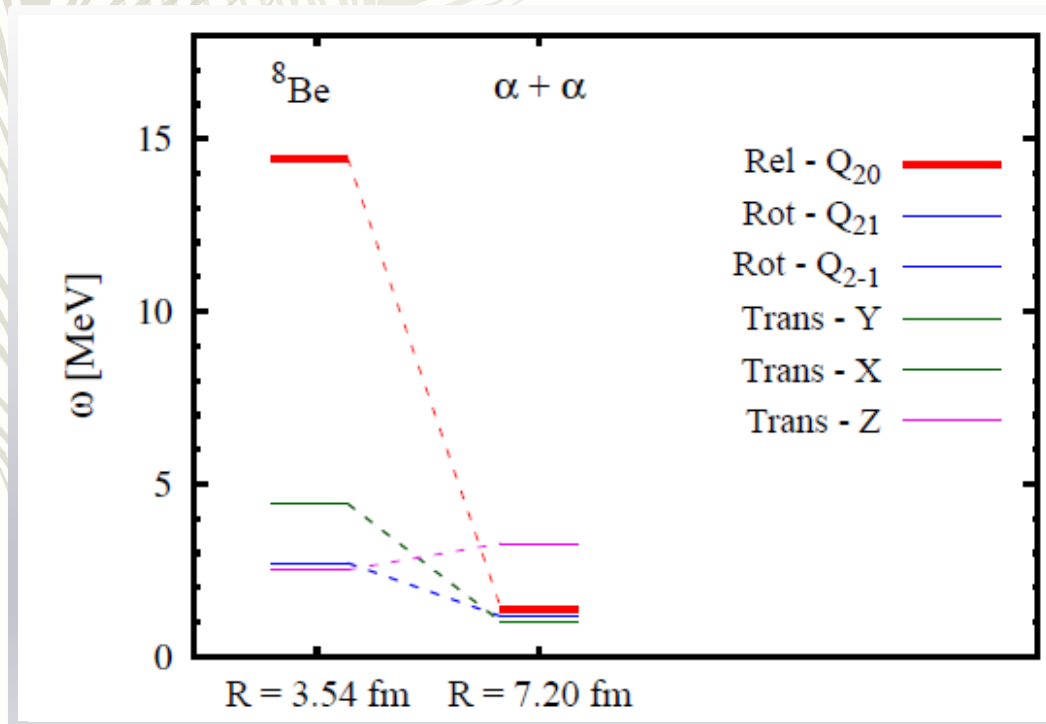
$$\hat{R} \equiv \frac{1}{A/2} \int d\vec{r} \hat{\psi}^\dagger(\vec{r}) \hat{\psi}(\vec{r}) \{z\theta(z) - z\theta(-z)\}$$



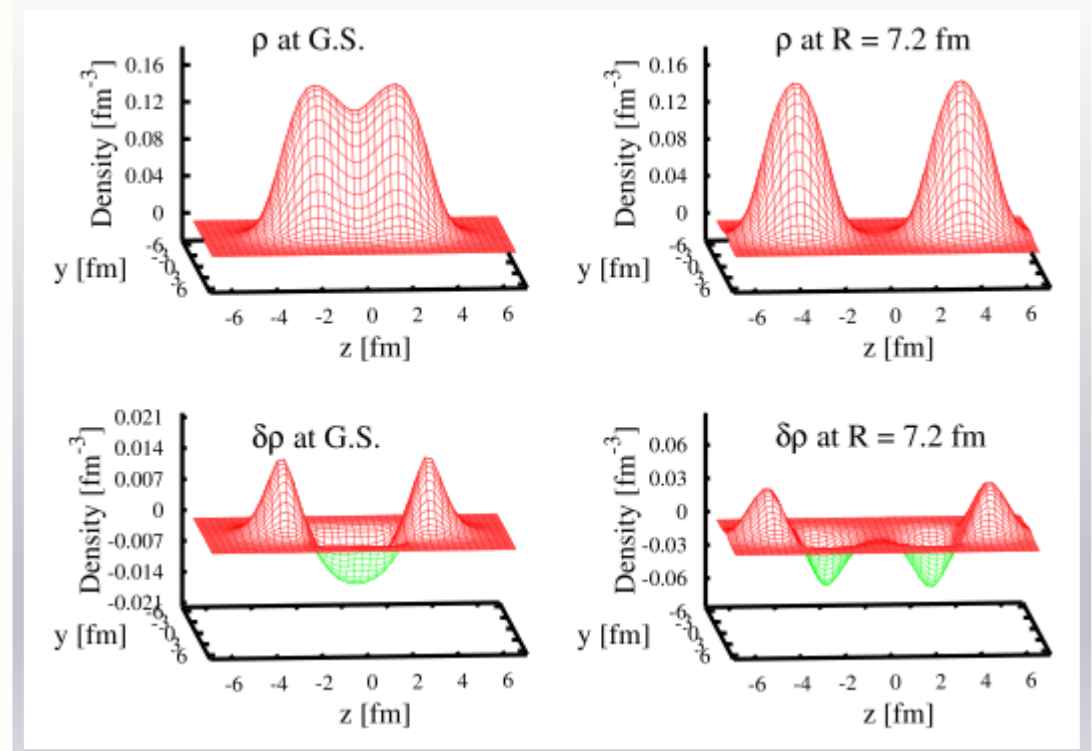
CHF+LRPA mass for ${}^8\text{Be} \leftrightarrow \alpha + \alpha$

- Calculation in 3D coordinate space. In the rectangular box of volume $10 \times 10 \times 16 \text{ fm}^3$ with grid size 0.8 fm .

RPA eigenvalues

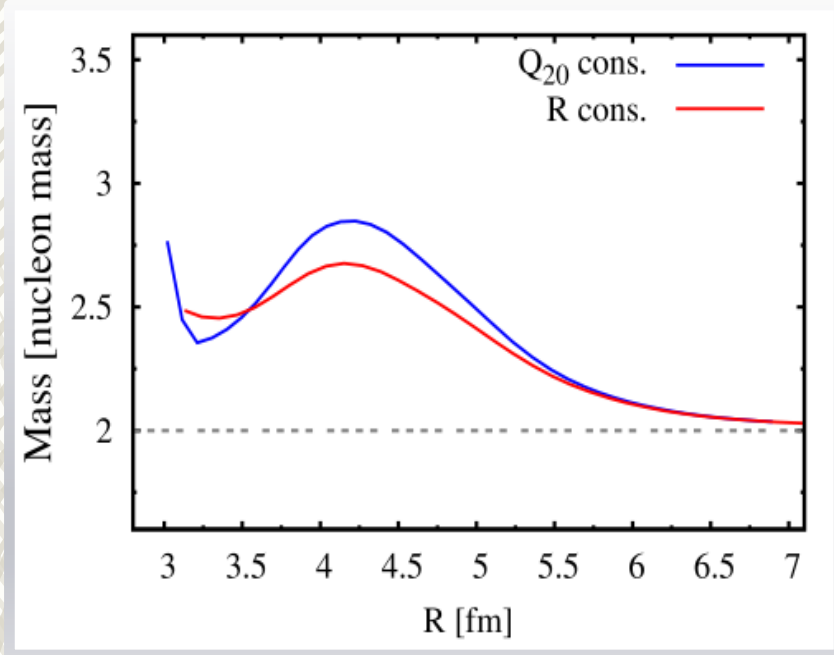


Density and transition density

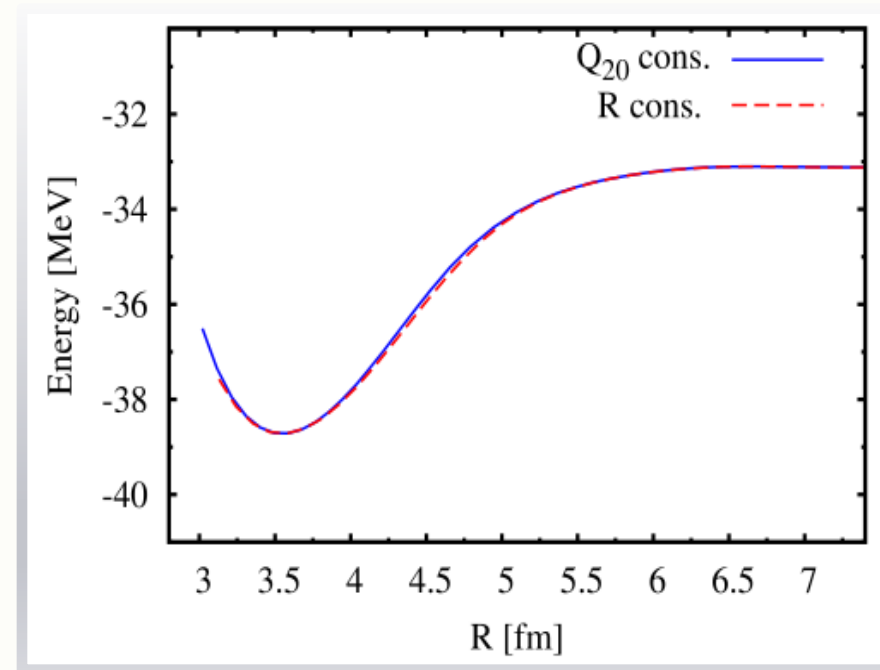


CHF+RPA mass and potential of CHF states

Inertial Mass with coordinate R



Potential energy of CHF states



Results depend on the choice of the constraint.

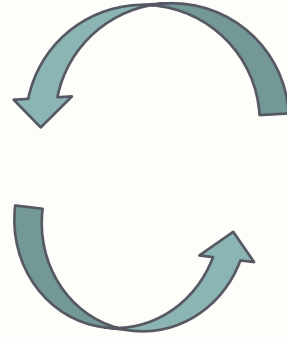


Content:

- ❑ The Adiabatic Self-consistent Collective Coordinate (ASCC) Method
- ❑ The inertial mass for ${}^8\text{Be} \leftrightarrow \alpha + \alpha$.
 - CHF+LRPA mass
 - **ASCC mass**
 - Cranking mass and ATDHF
- ❑ The ASCC collective motion paths.
- ❑ Summary

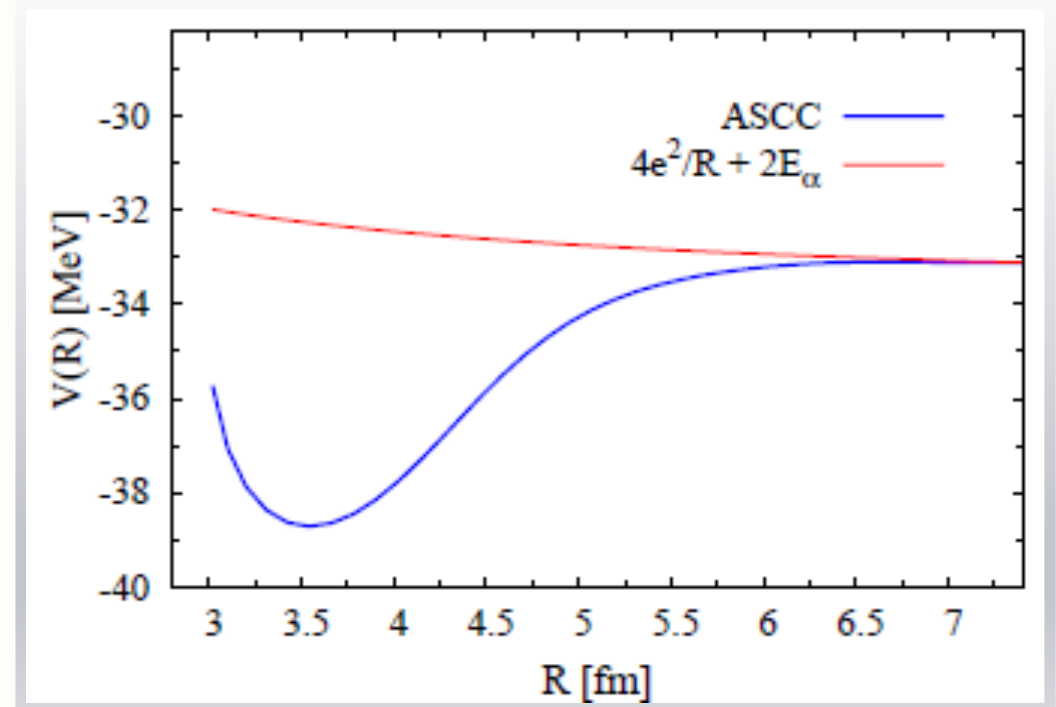
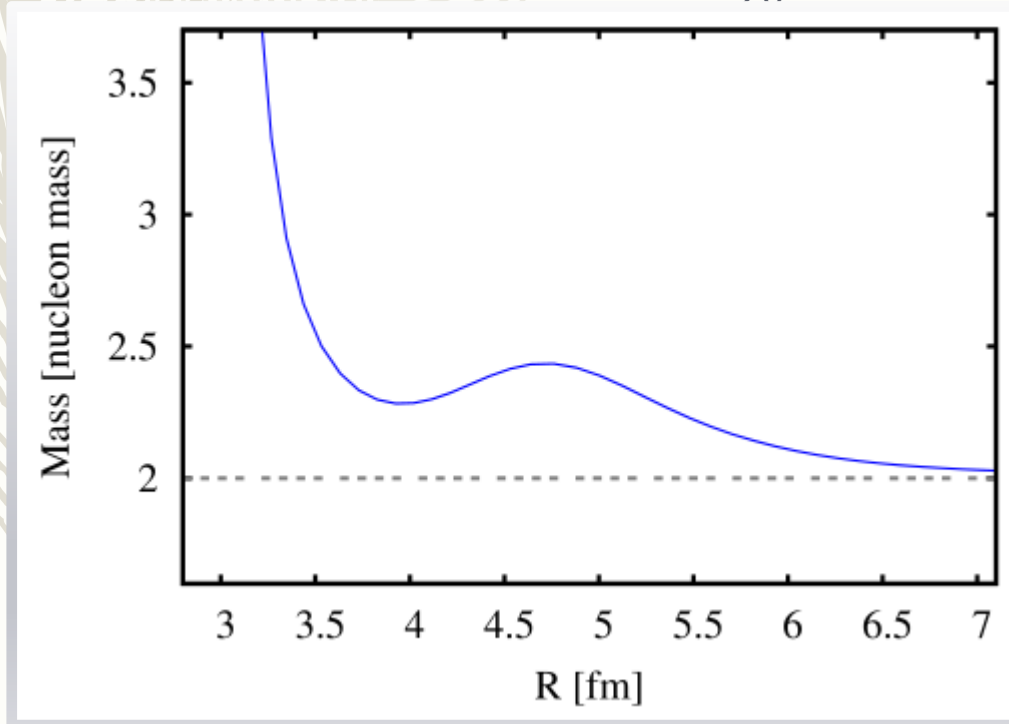
ASCC mass: fission path ${}^8\text{Be}$

$$\delta\langle\psi(q)|\hat{H}_{\text{mv}}(q)|\psi(q)\rangle = 0$$



$$\delta\langle\psi(q)|[\hat{H}_{\text{mv}}(q), \frac{1}{i}\hat{P}(q)] - \frac{\partial^2 V}{\partial q^2}\hat{Q}(q)|\psi(q)\rangle = 0,$$
$$\delta\langle\psi(q)|[\hat{H}_{\text{mv}}(q), i\hat{Q}(q)] - \frac{1}{M(q)}\hat{P}(q)|\psi(q)\rangle = 0,$$

Iteration starts from the Q_{20} and R constrained state respectively, M converges



Self-consistency of CHF+LRPA and ASCC mass

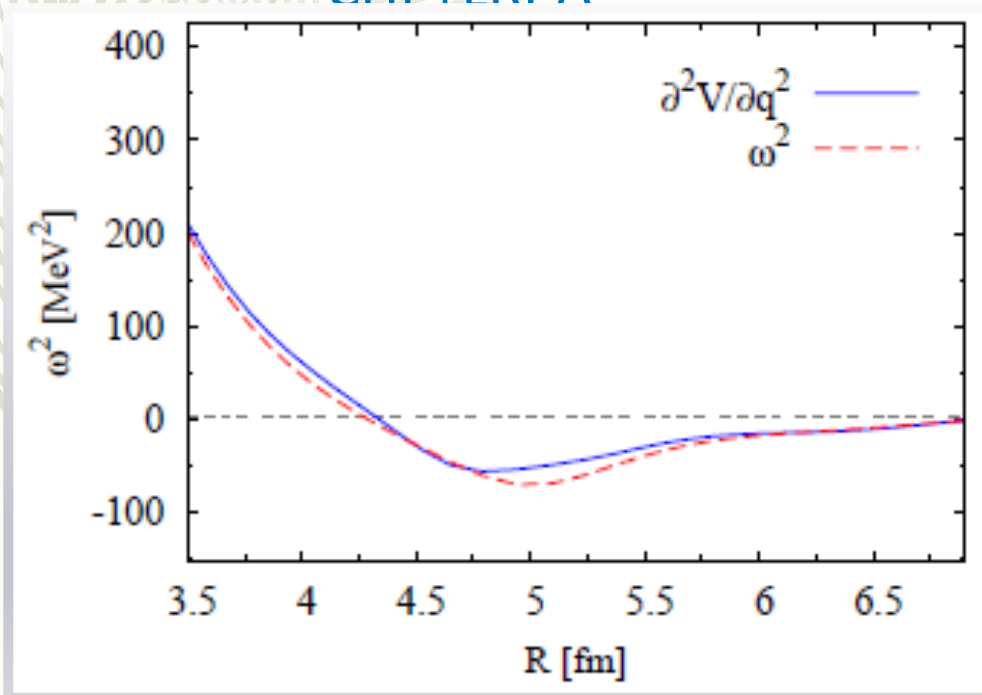
Whether the collective path follows the direction defined by the local generators?

- ❑ Interpretation of RPA eigenvalue ω^2 :
- ❑ The second order derivative of CHF potential:

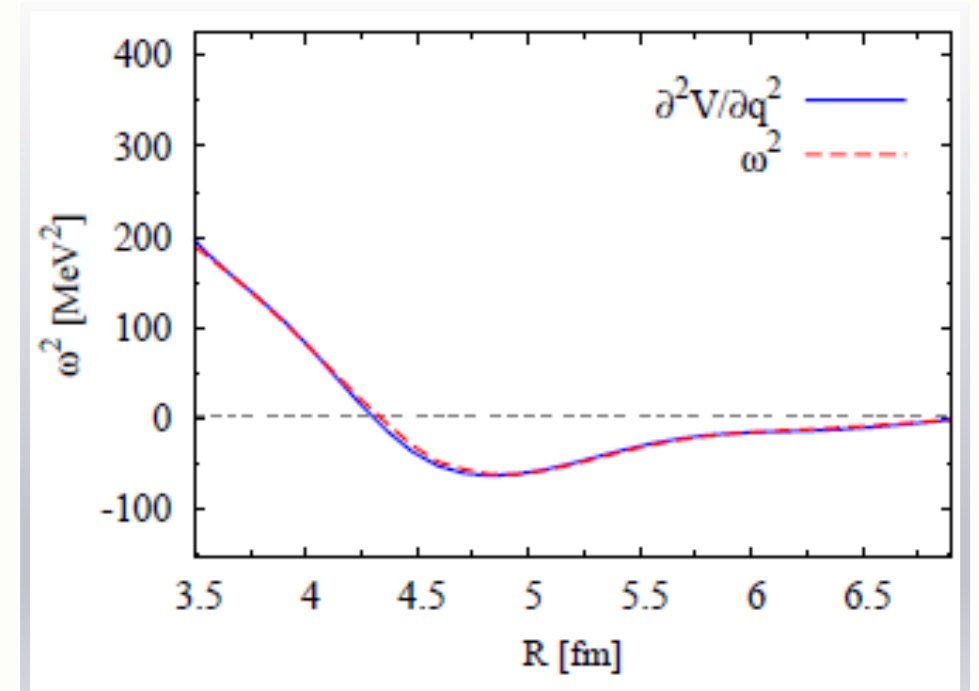
$$\omega^2 = \frac{d^2 V_{\text{local}}}{dq^2}$$

$$\frac{d^2 V}{dq^2} = \frac{d^2 V}{dR^2} \left(\frac{dR}{dq} \right)^2 = \frac{d^2 V}{dR^2} \frac{1}{M}$$

CHF+LRPA



ASCC





Content:

- ❑ The Adiabatic Self-consistent Collective Coordinate (ASCC) Method
- ❑ The inertial mass for ${}^8\text{Be} \leftrightarrow \alpha + \alpha$.
 - CHF+LRPA mass
 - ASCC mass
 - **Cranking mass and ATDHF**
- ❑ The ASCC collective motion paths.
- ❑ Summary

Cranking Mass

Inglis cranking mass
(non-perturbative cranking mass):

$$M_{\text{cr}}^{\text{NP}}(R) = 2 \sum_{m,i} \frac{|\langle \varphi_m(R) | \partial / \partial R | \varphi_i(R) \rangle|^2}{e_m(R) - e_i(R)},$$

$$h_{\text{CHF}}(R) |\varphi_\mu(R)\rangle = e_\mu(R) |\varphi_\mu(R)\rangle, \quad \mu = i, m.$$

D. R. Inglis, Phys.Rev. 96, 1059(1954);
D. R. Inglis, Phys.Rev. 103, 1786(1956);

... ..

Perturbative cranking mass:

$$M_{\text{cr}}^{\text{P}}(R) = \frac{1}{2} \left\{ S^{(1)}(R) \right\}^{-1} S^{(3)}(R) \left\{ S^{(1)}(R) \right\}^{-1},$$

with

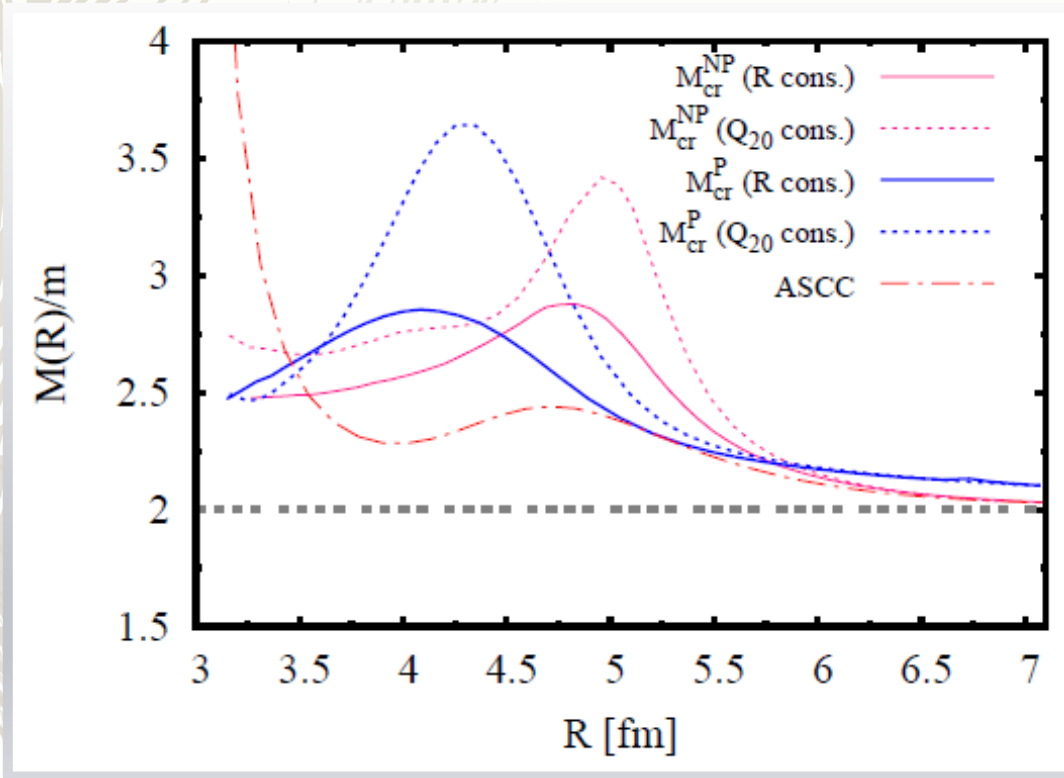
$$S^{(k)}(R) = \sum_{m,i} \frac{|\langle \varphi_m(R) | \hat{R} | \varphi_i(R) \rangle|^2}{\{e_m(R) - e_i(R)\}^k}.$$

A. Baran et. al. Phys. Rev. C **84**, 054321(2011);
D. Vautherin Phys. Lett.69B, 4(1977);

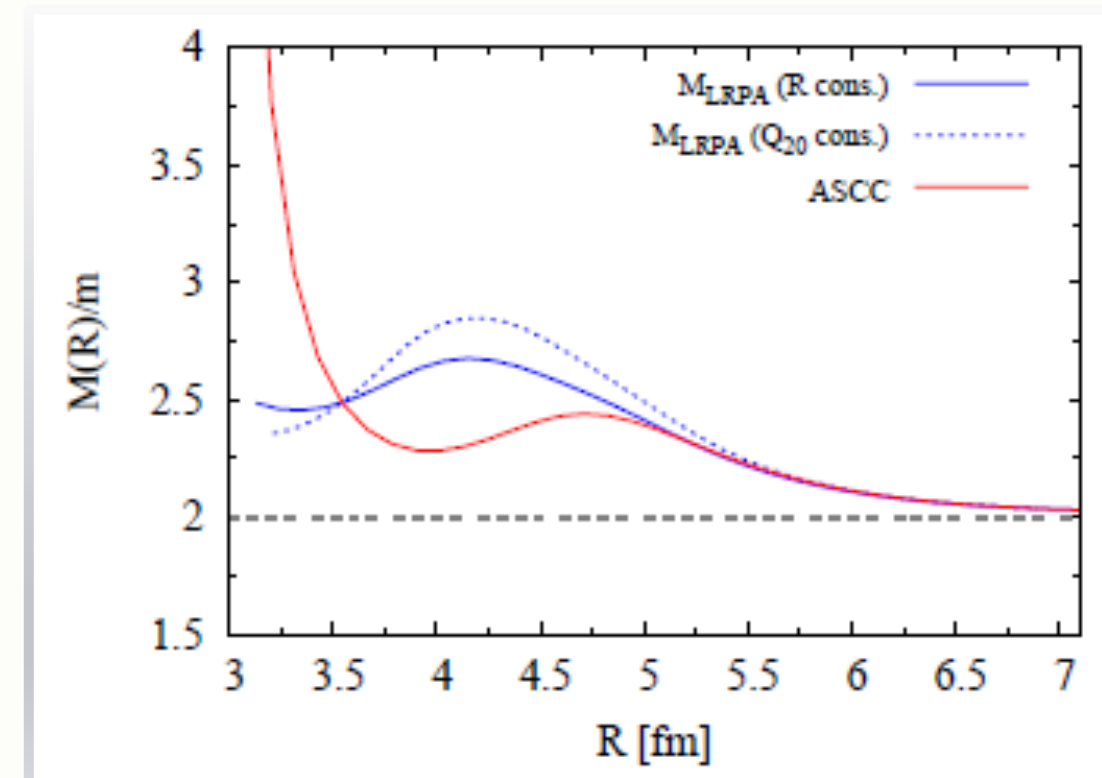
... ..

Comparison between different masses

Cranking and ASCC



CHF+LRPA and ASCC



Adiabatic Time-Dependent Hartree-Fock(ATDHF)

➤ Equation for the collective path $\psi(q)$:

$$\frac{\partial}{\partial q} |\psi(q)\rangle = \frac{M_{\text{atdhf}}(q)}{dV/dq} [\hat{H}, \hat{H}_{\text{ph}}]_{\text{ph}} |\psi(q)\rangle,$$

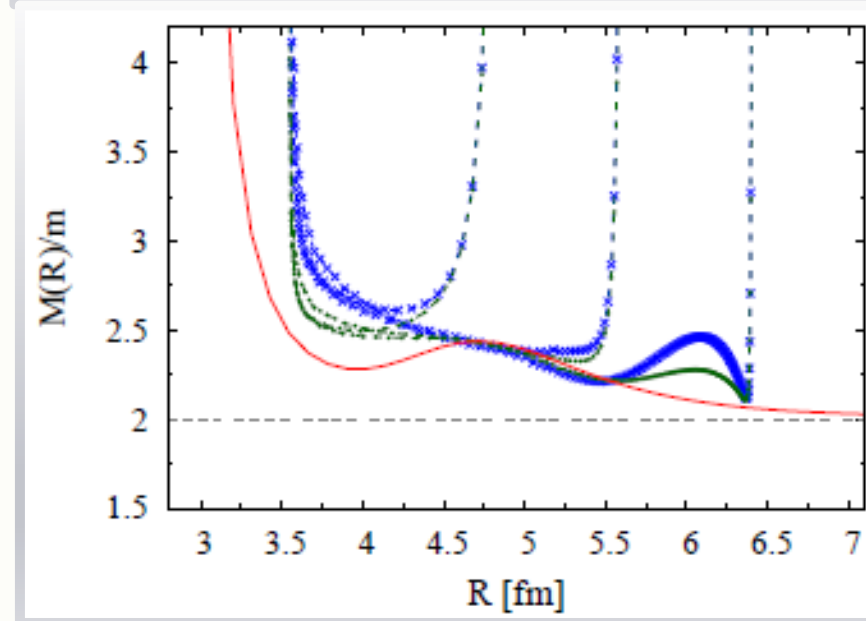
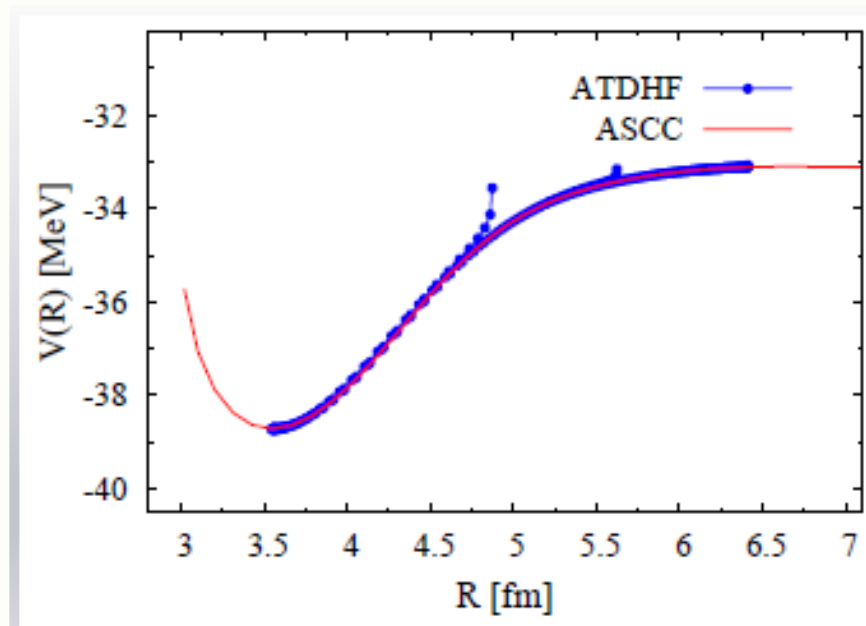
➤ Mass parameter can be calculated in two way:

○ (1)
$$M_{\text{atdhf}}(R) = \left(\frac{dV}{dR} \right)^2 \langle \psi(q) | [\hat{H}_{\text{ph}}(q), [\hat{H}, \hat{H}_{\text{ph}}(q)]] | \psi(q) \rangle^{-1}.$$

○ (2)
$$M_{\text{atdhf}}(R) = \left(\frac{dq}{dR} \right)^2 \frac{\varepsilon}{\delta q} \frac{dV}{dq} = \frac{\varepsilon}{\delta R} \frac{dV}{dR}.$$

➤ Drawbacks:

- Non-uniqueness(initial value problem)
- Trajectory can only go from high energy to low energy
- Difficult to find find the saddle point





Content:

❑ The Adiabatic Self-consistent Collective Coordinate (ASCC) Method

❑ The inertial mass for ${}^8\text{Be} \leftrightarrow \alpha + \alpha$.

❑ **The ASCC collective motion paths.**



❑ Summary

Procedure to develop the collective path

$\Psi(q)$

Initial state

$$\begin{aligned} \delta\langle\Psi(q)|[\hat{H}_{\text{mv}}(q), \frac{1}{i}\hat{P}(q)] - \frac{\partial^2 V}{\partial q^2}\hat{Q}(q)|\Psi(q)\rangle &= 0, \\ \delta\langle\Psi(q)|[\hat{H}_{\text{mv}}(q), i\hat{Q}(q)] - \frac{1}{M(q)}\hat{P}(q)|\Psi(q)\rangle &= 0, \end{aligned}$$

Moving RPA equation

$$\begin{aligned} \delta\langle\Psi(q+\varepsilon)|H - \frac{\partial V}{\partial q}\hat{Q}(q)|\Psi(q+\varepsilon)\rangle &= 0, \\ \langle\Psi(q+\varepsilon)|\hat{Q}(q)|\Psi(q+\varepsilon)\rangle|_{q=0} &= \varepsilon, \end{aligned}$$

CHF problem

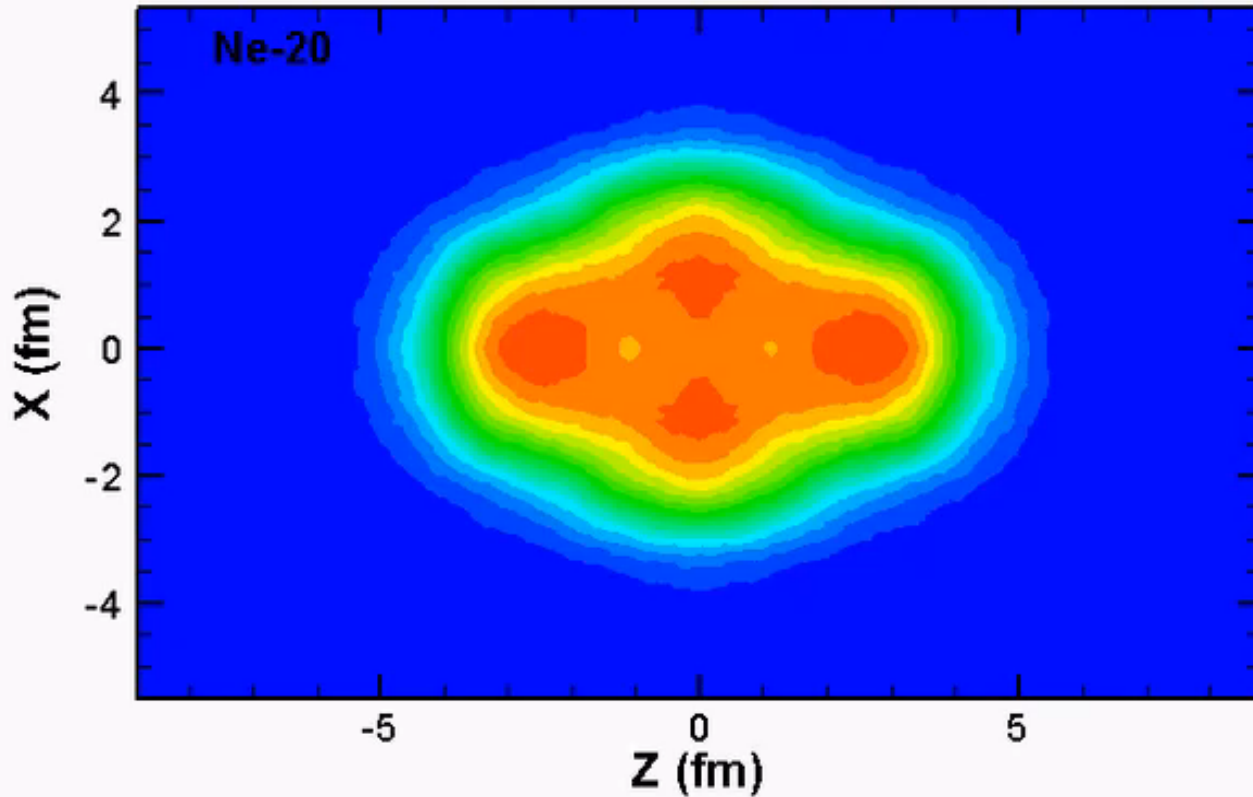
$\Psi(q+\varepsilon)$

Continue the iteration, we get a collective path:

$$\Psi(q), \Psi(q+\varepsilon), \Psi(q+2\varepsilon), \Psi(q+3\varepsilon), \Psi(q+4\varepsilon)\dots$$

When ε is small enough, the states on the trajectory keeps well the original self-consistency in the ASCC equation set.

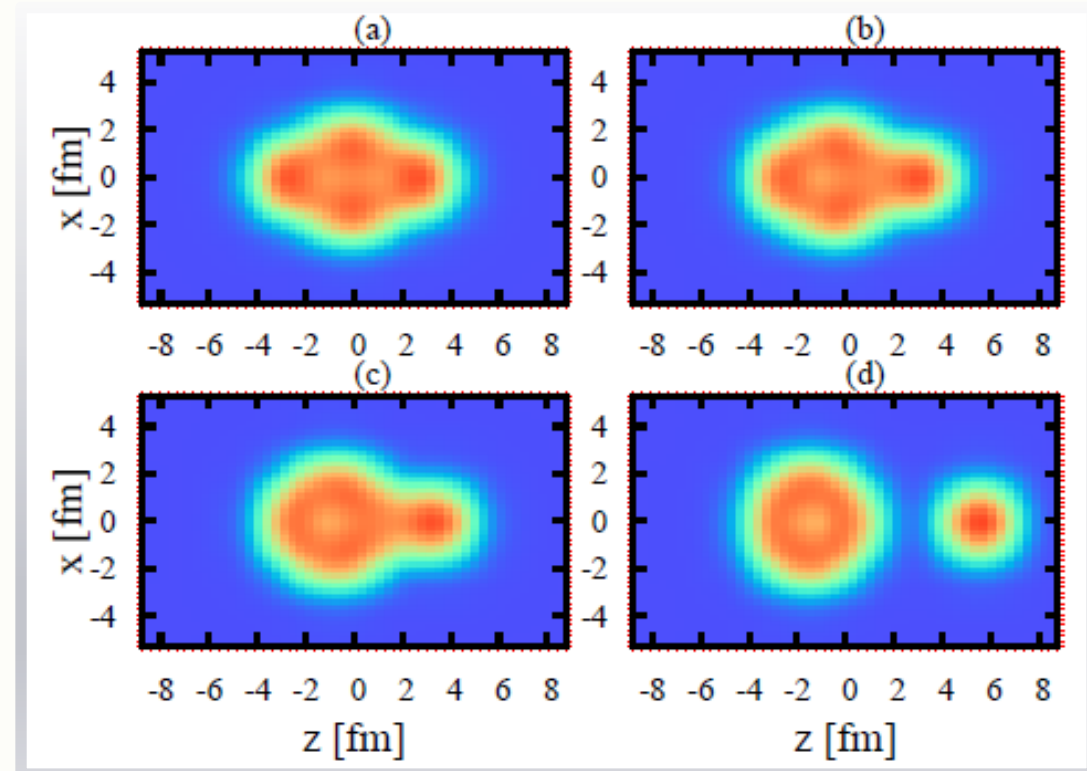
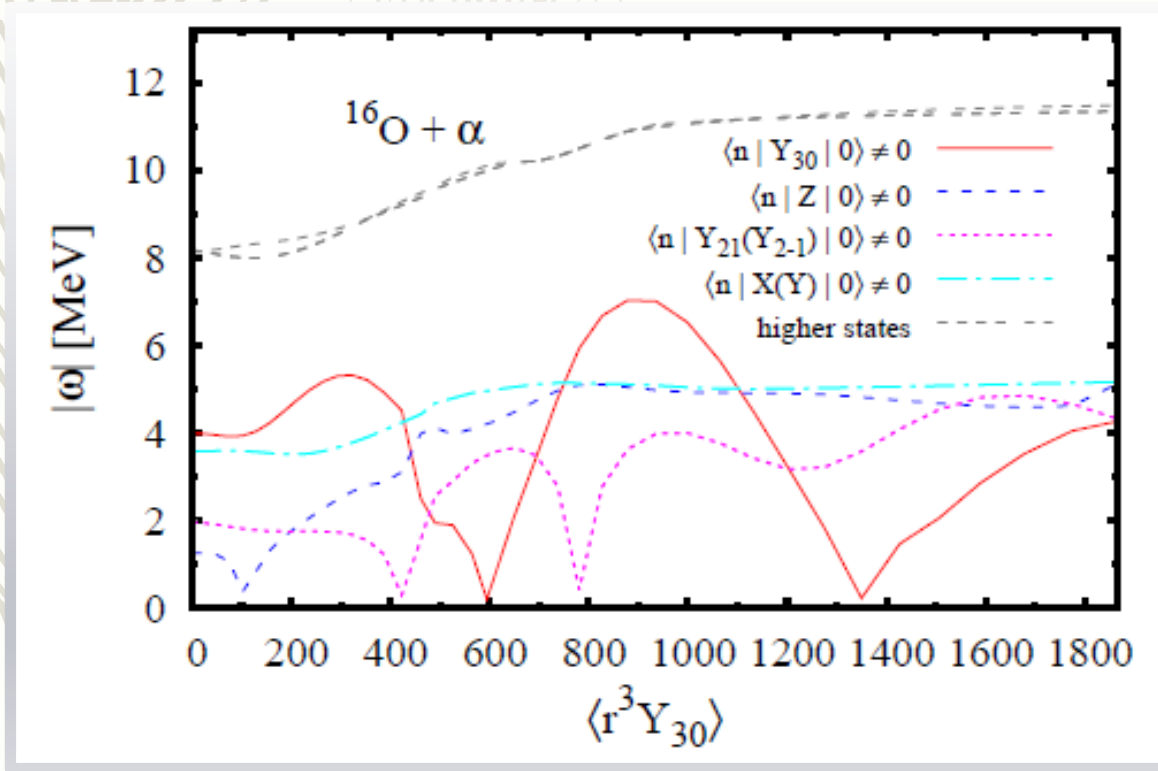
Collective motion path of fission from ^{20}Ne to $^{16}\text{O} + \alpha$



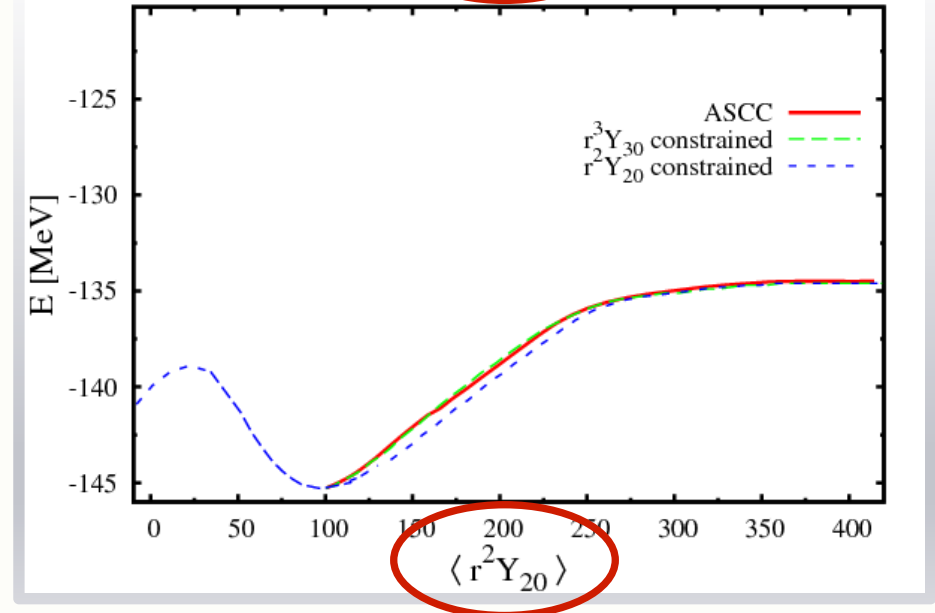
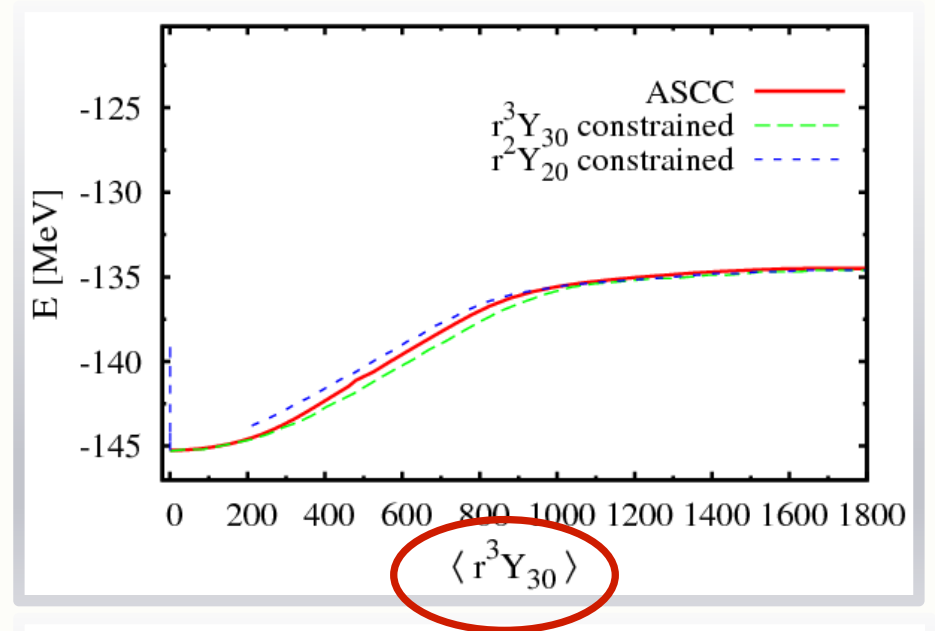
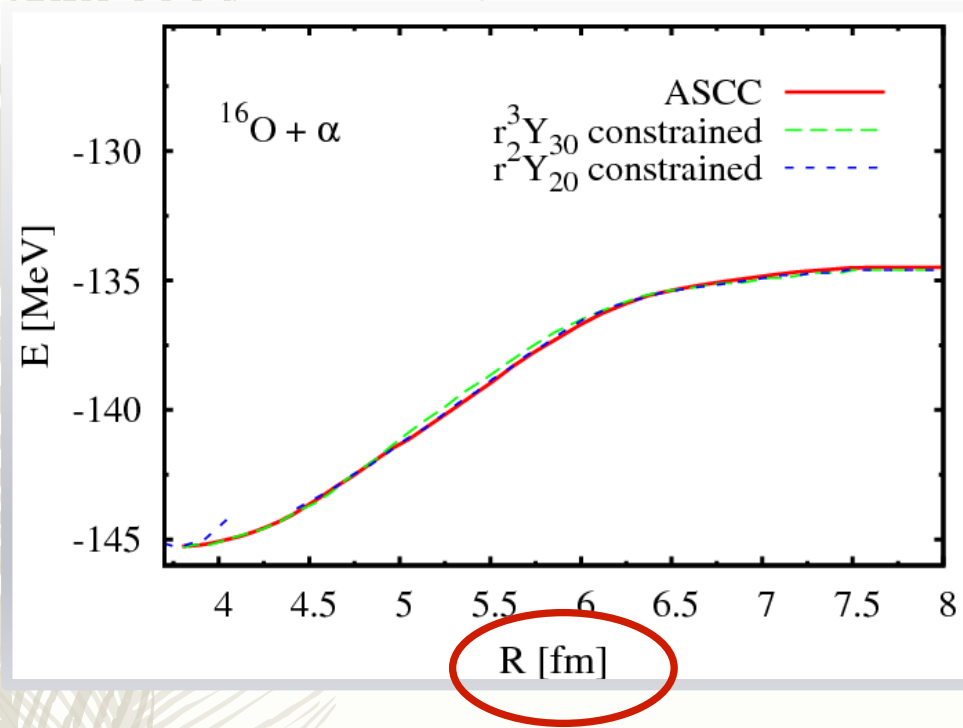
- Starting from the ^{20}Ne at ground state, end up with $^{16}\text{O} + \alpha$
- The first physical RPA state with axial symmetry is used to develop the trajectory.
- Model space: rectangular box of $12 \times 12 \times 18 \text{ fm}^3$ with grid size 1.1 fm.

Collective motion path of $^{16}\text{O} + \alpha$

Eigen frequency of the RPA states along the ASCC collective path

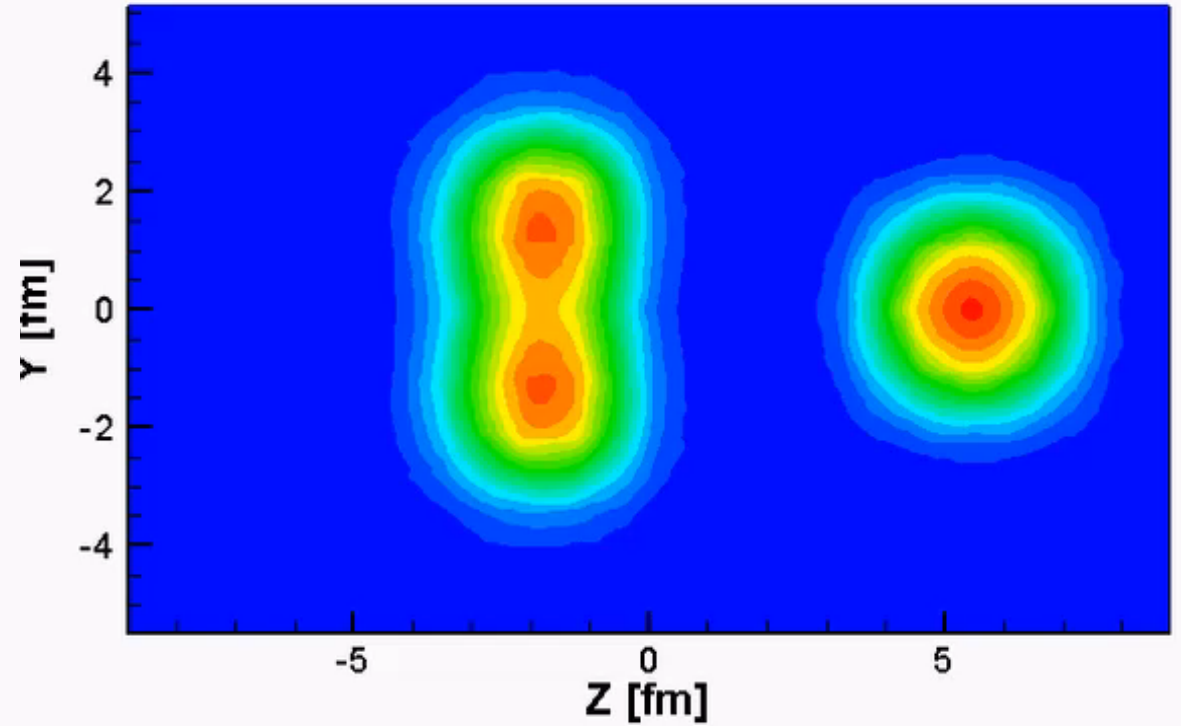
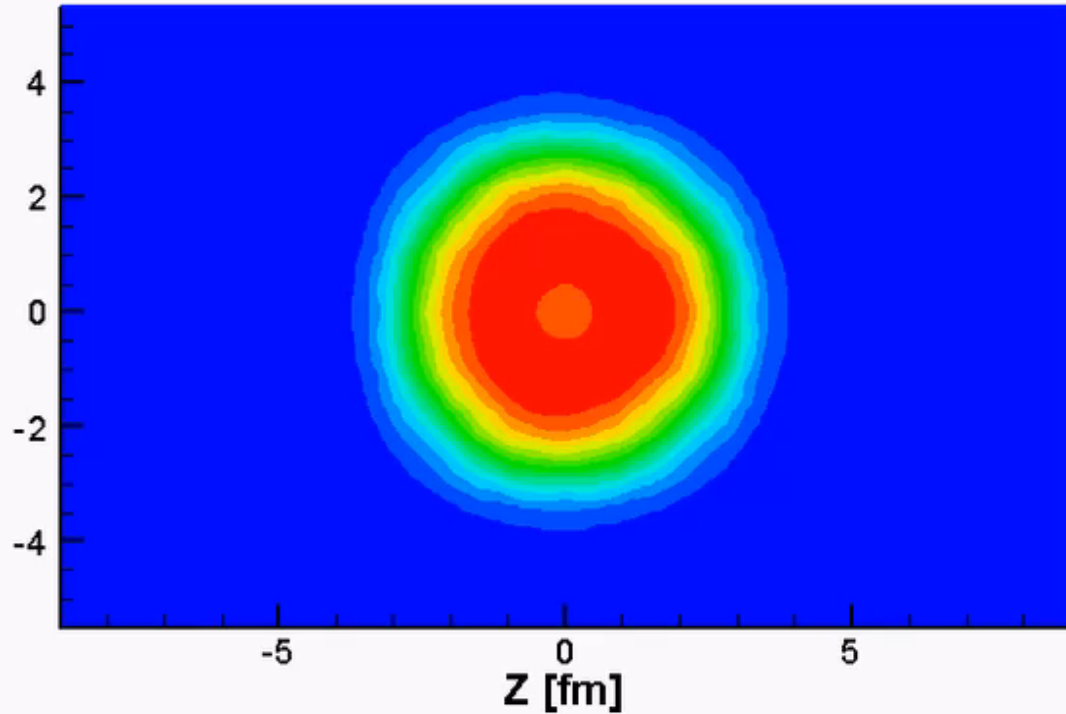


Potential of the system $^{16}\text{O} + \alpha$



The ASCC path deviates slightly from the quadrupole or octupole deformation constrained states

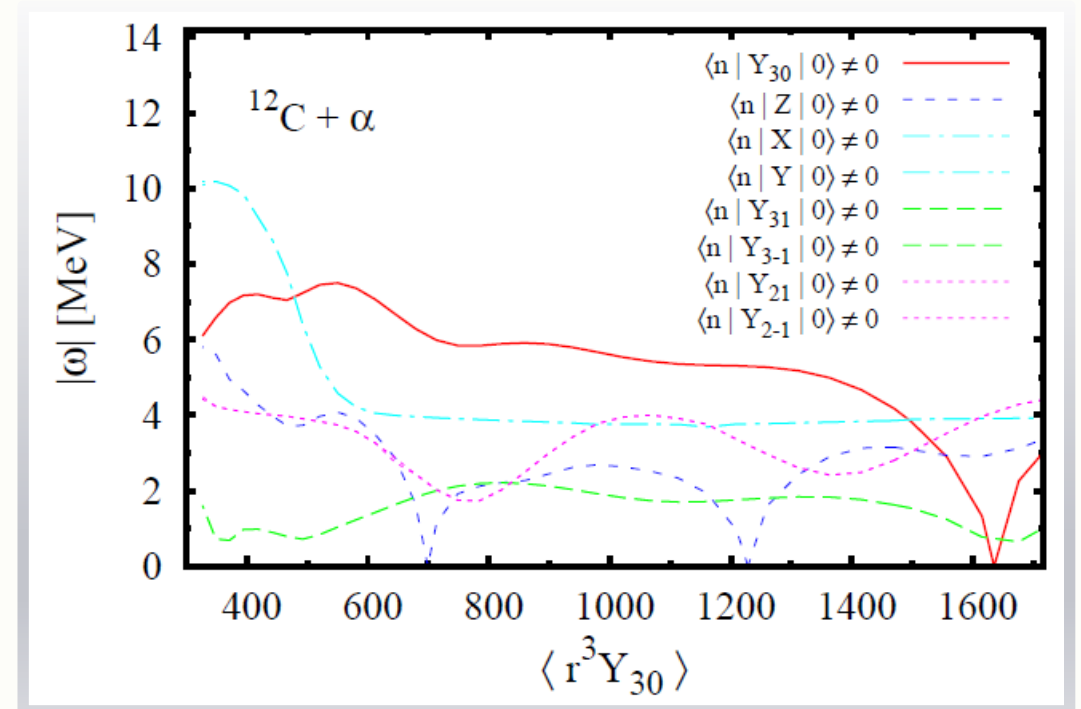
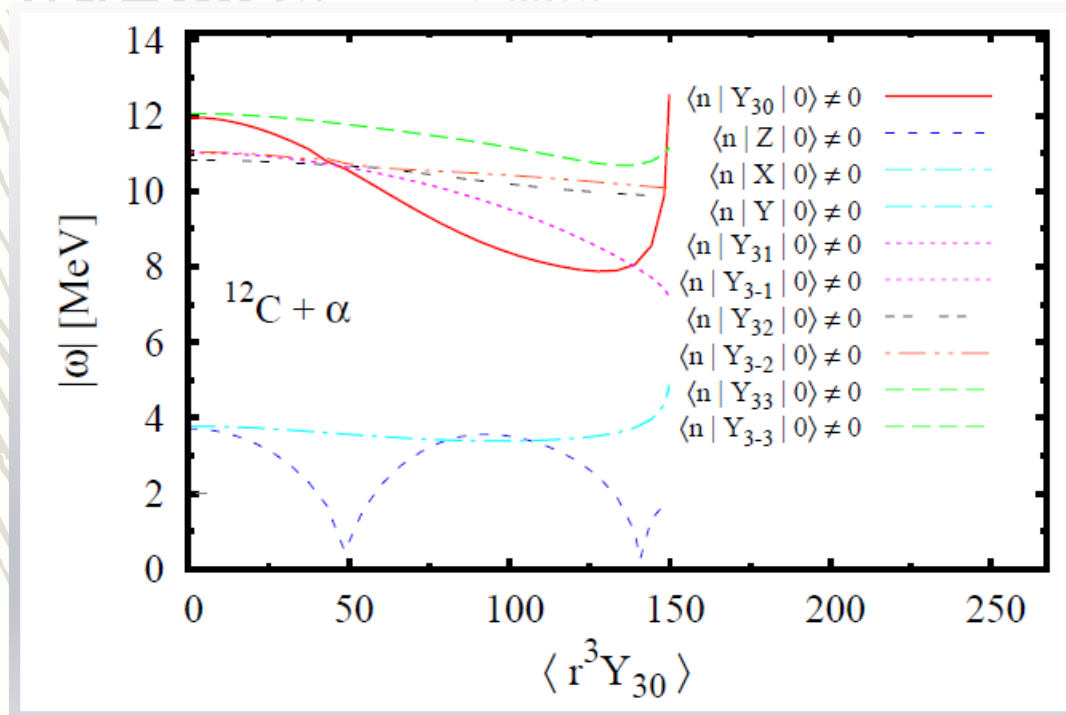
Collective motion path of fission from ^{16}O to $^{12}\text{C} + \alpha$



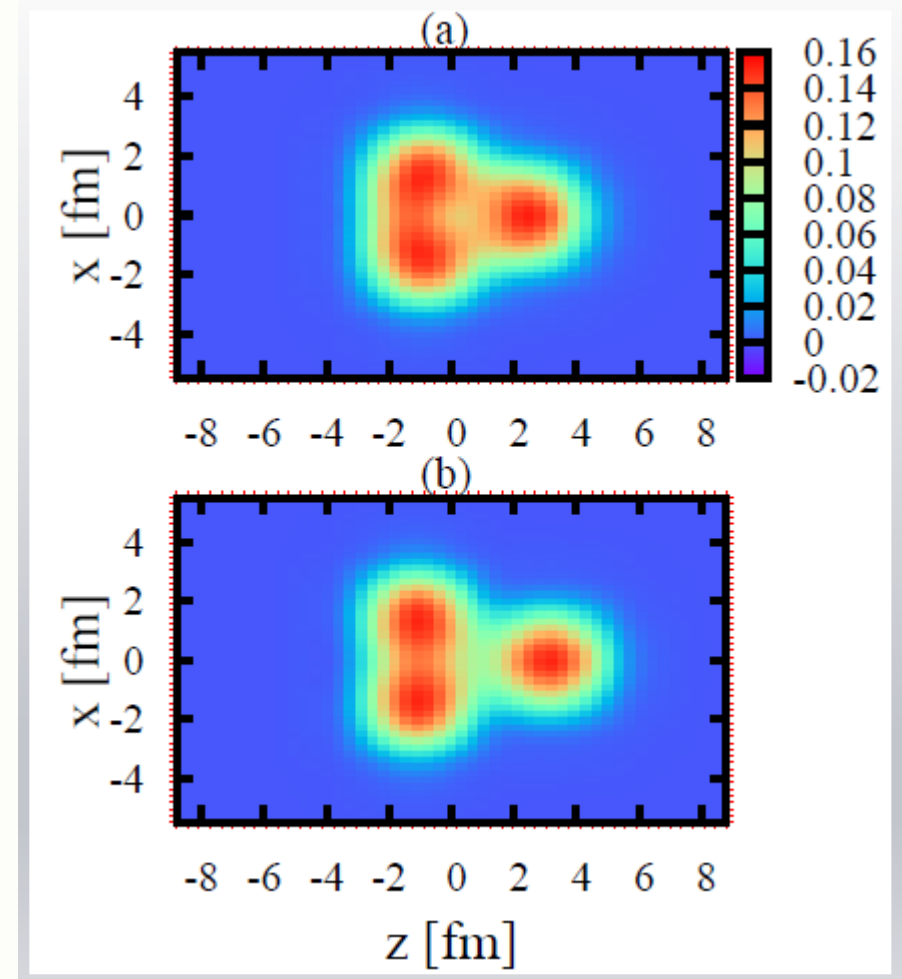
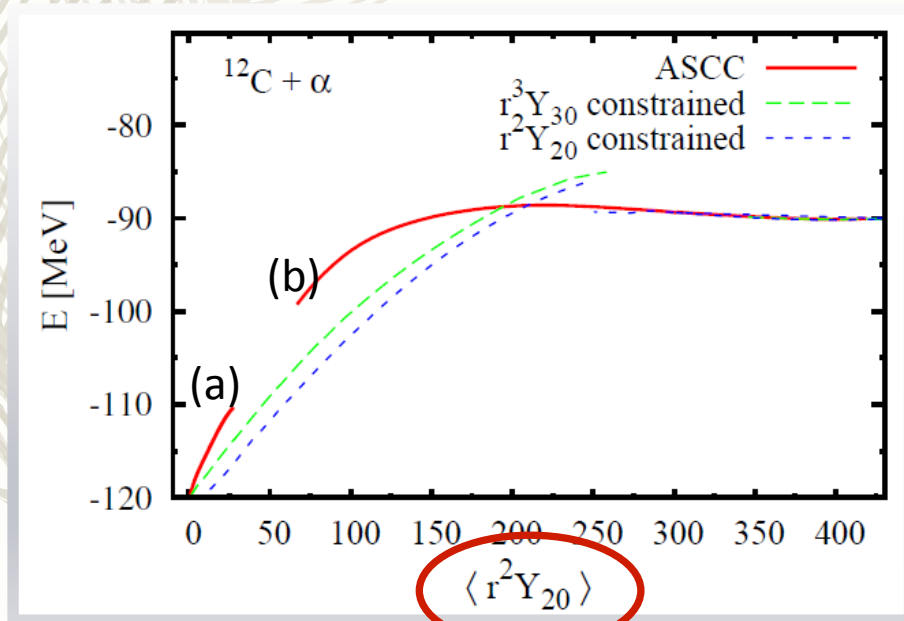
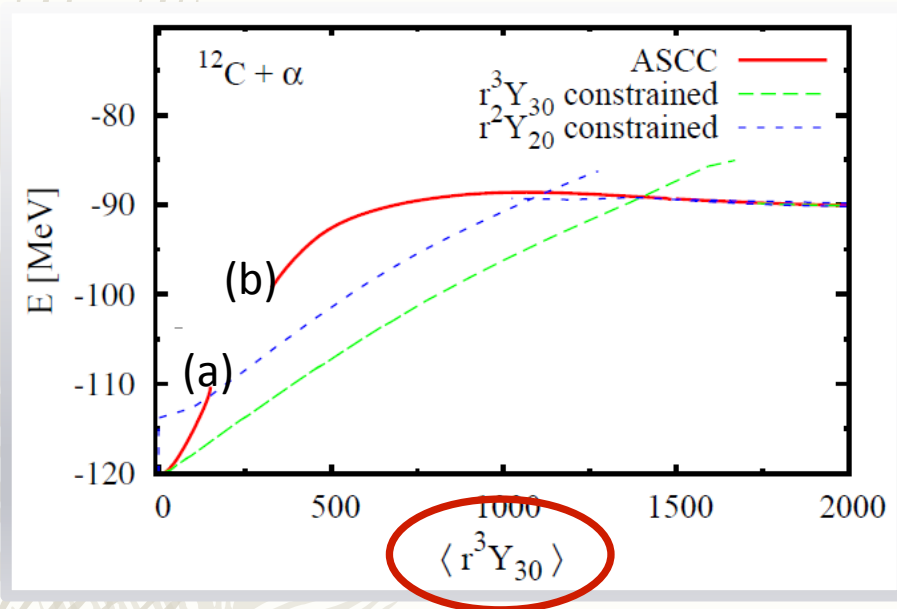
- Starting from the ^{16}O ($^{12}\text{C} + \alpha$)
- The first physical RPA state with axial symmetry is used to develop the trajectory.
- Model space: rectangular box of $12 \times 12 \times 18 \text{ fm}^3$ with grid size 1.1 fm .

Collective motion path of $^{12}\text{C} + \alpha$

Eigen frequency of the RPA states along the ASCC collective path



Results of the system $^{12}\text{C} + \alpha$ in large model space

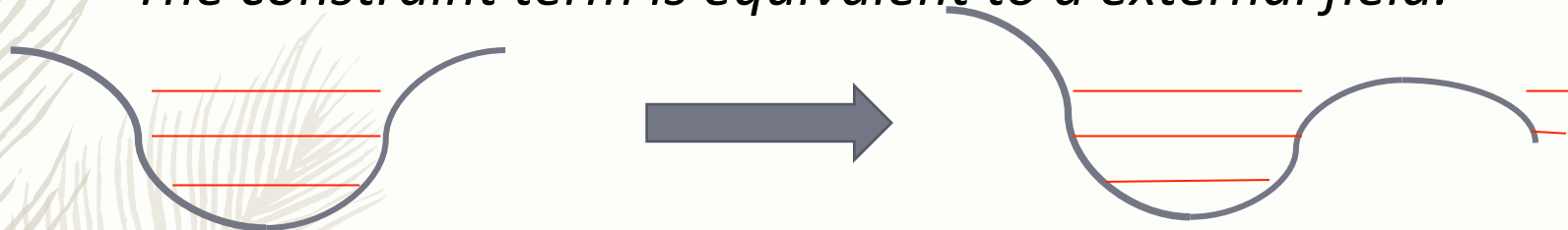


Model space: rectangular box of $12 \times 12 \times 18$ fm^3 with grid size 1.1 fm.

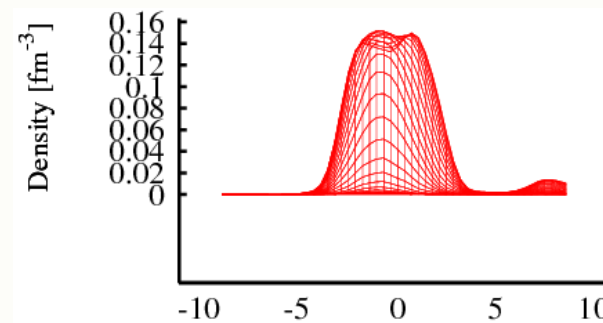
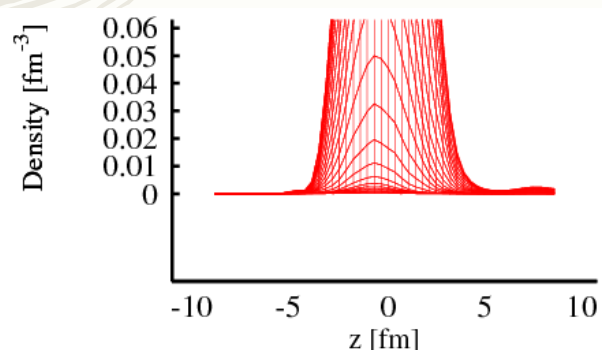
A problem in the constrained Hartree Fock calculation

$$\delta\langle\psi|H - \lambda Q_{20}(Q_{30})|\psi\rangle = 0.$$

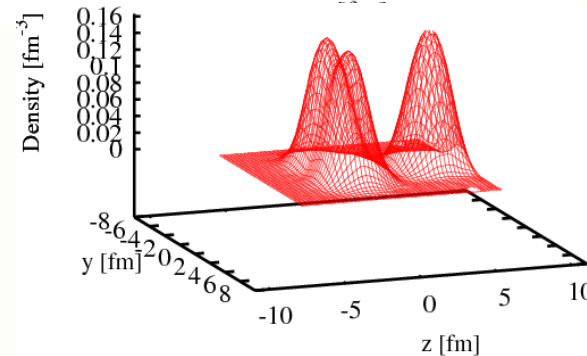
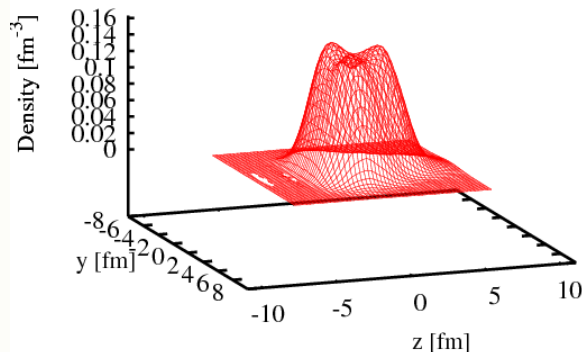
The constraint term is equivalent to a external field.



Large space :



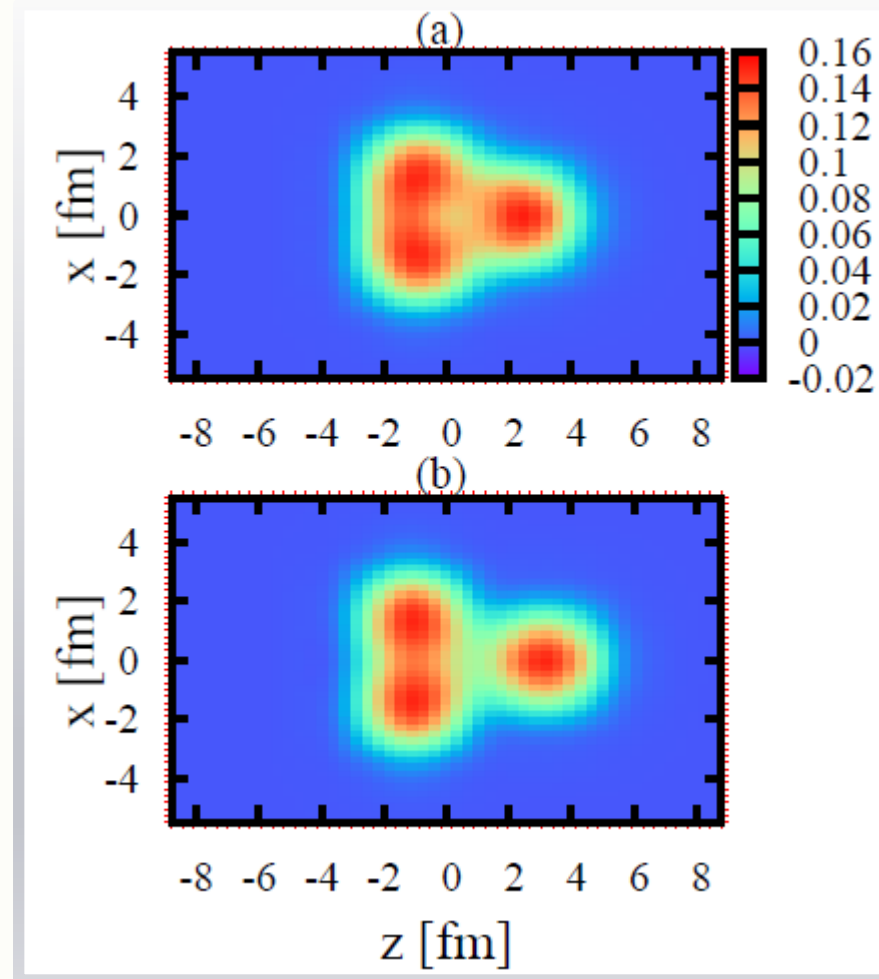
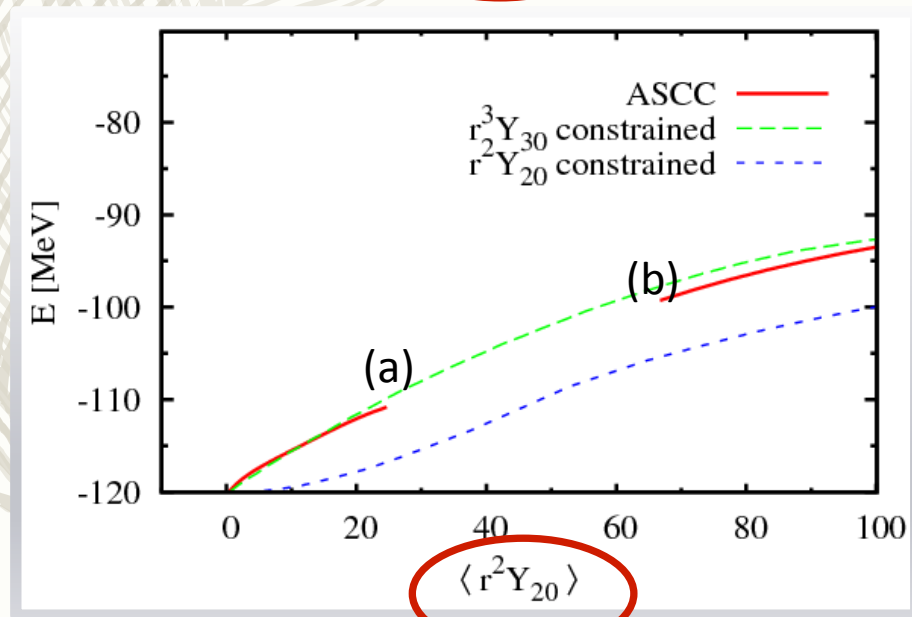
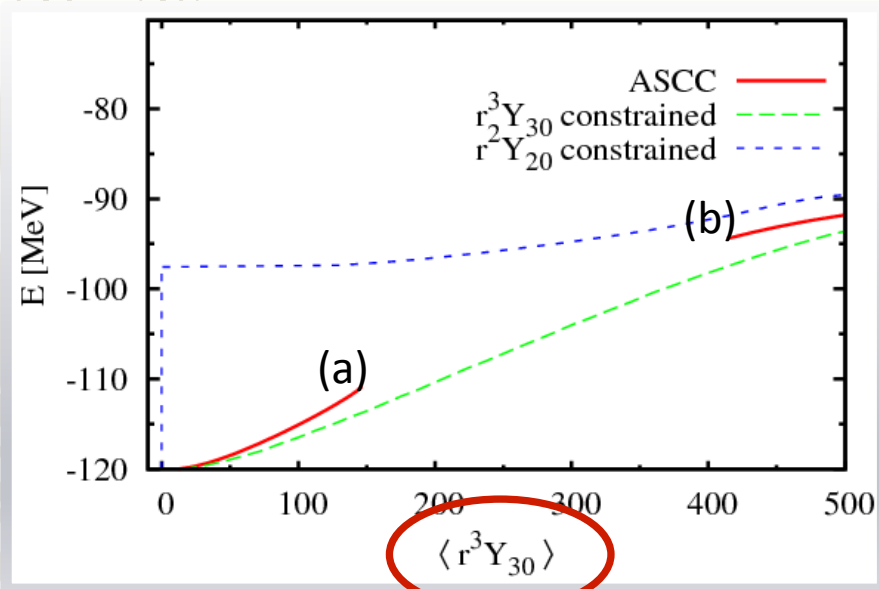
Small space :



$$\langle r^3 Y_{30} \rangle = 300$$

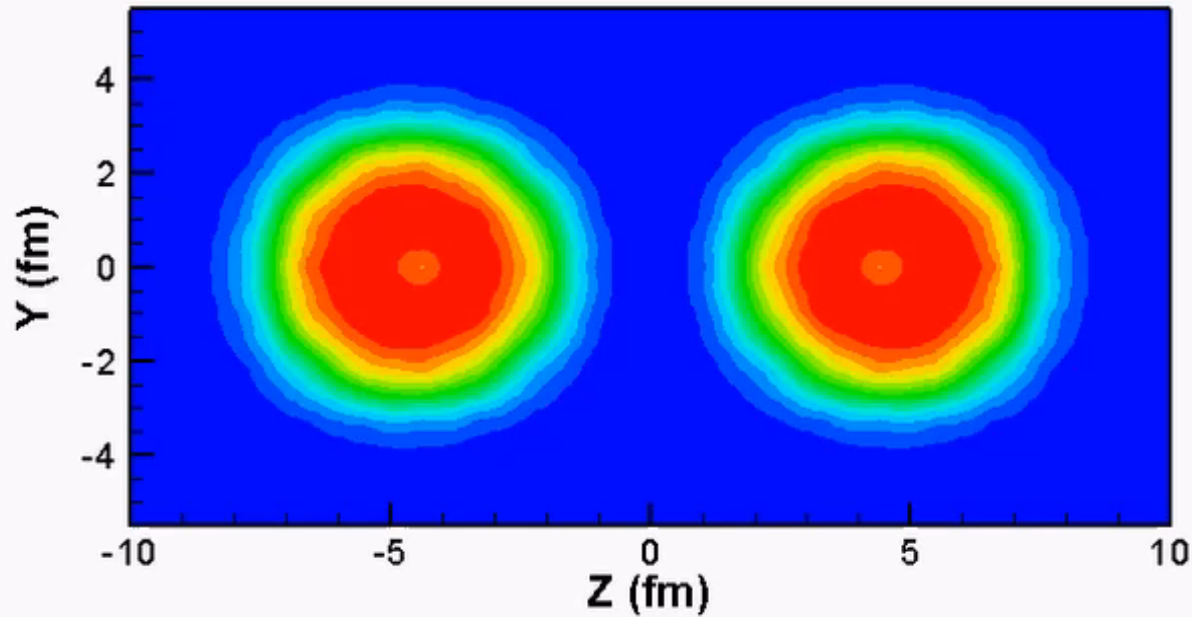
$$\langle r^3 Y_{30} \rangle = 900$$

Results of the system $^{12}\text{C} + \alpha$ in small model space



Model space: rectangular box of $12 \times 12 \times 14$ fm^3 with grid size 1.1 fm.

Collective motion path of scattering between $^{16}\text{O} + ^{16}\text{O}$

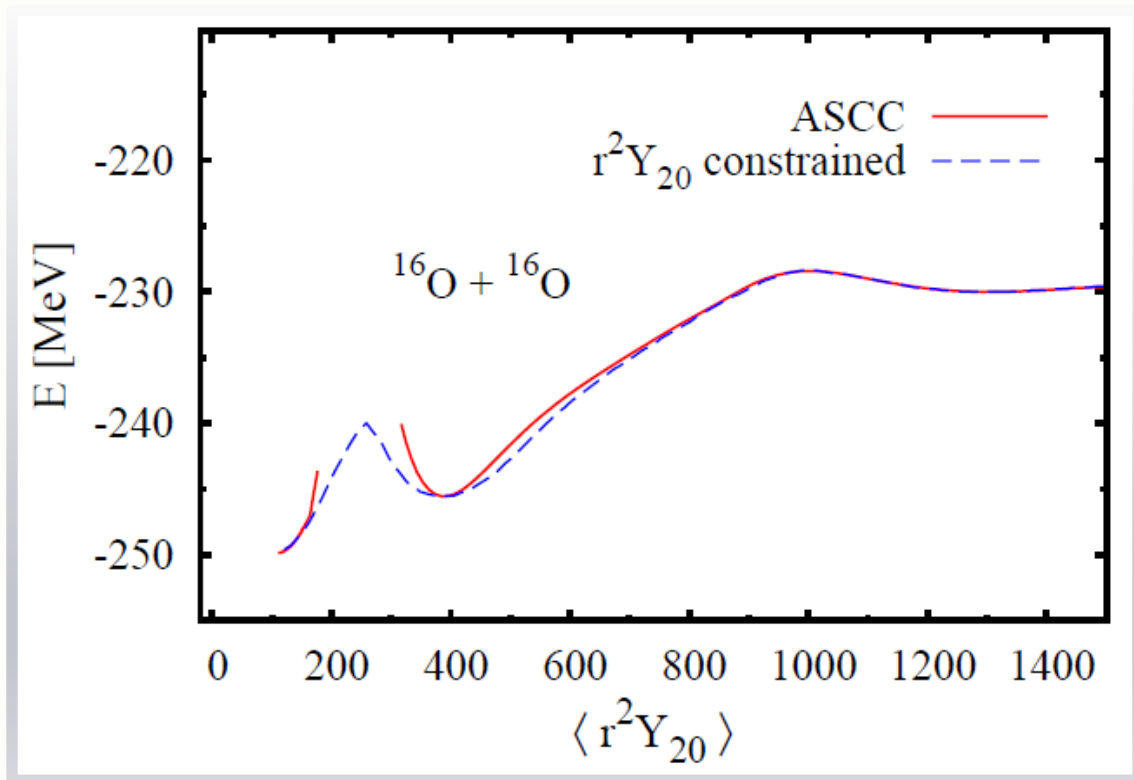
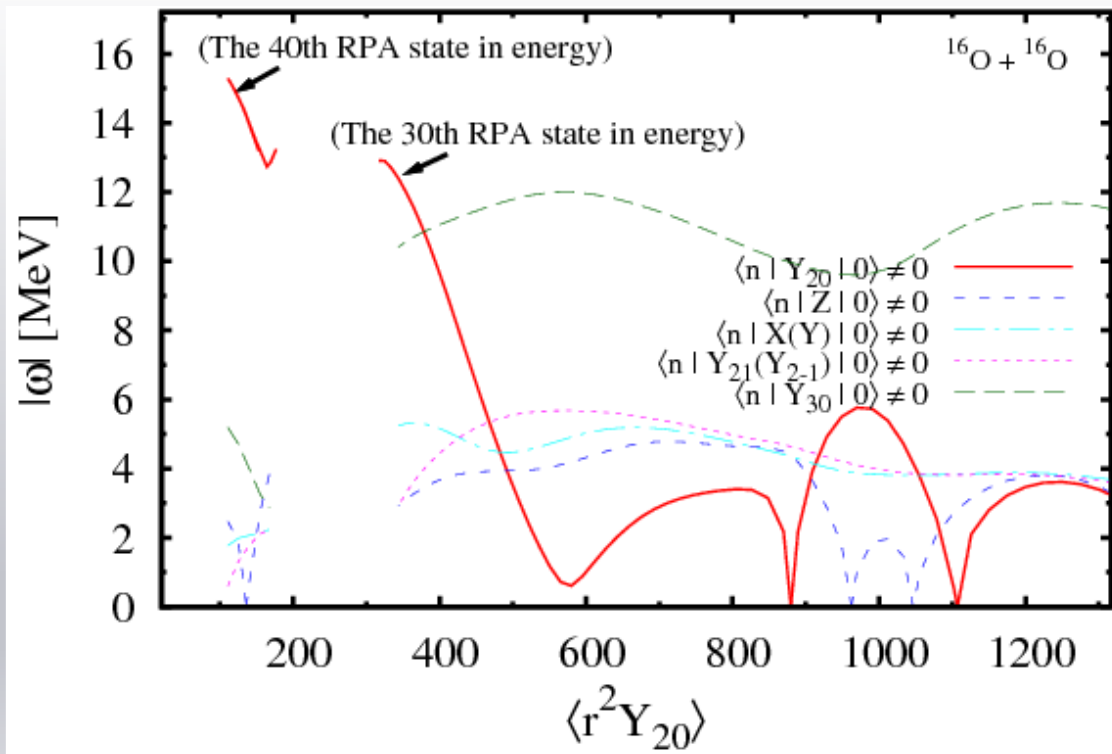


- Starting from the separated $^{16}\text{O} + ^{16}\text{O}$ both at ground state.
- The first physical RPA state of quadrupole mode is used to develop the trajectory.
- Model space: rectangular box of $12 \times 12 \times 22 \text{ fm}^3$ with grid size 1.1 fm.

Collective motion path of $^{16}\text{O} + ^{16}\text{O}$

*Eigen frequency of the RPA states
along the ASCC collective path*

Potential



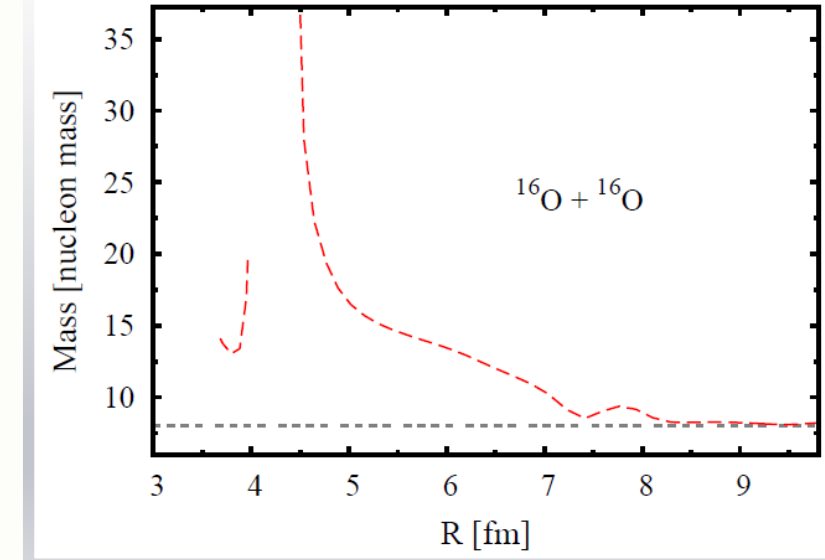
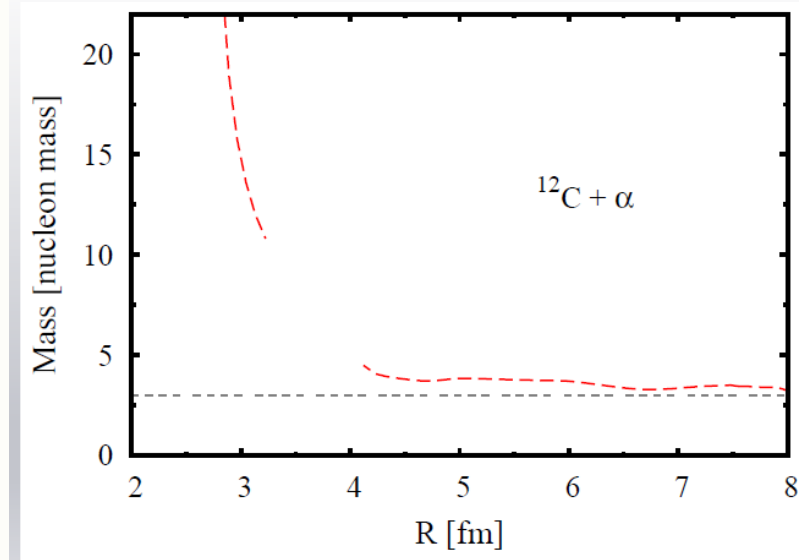
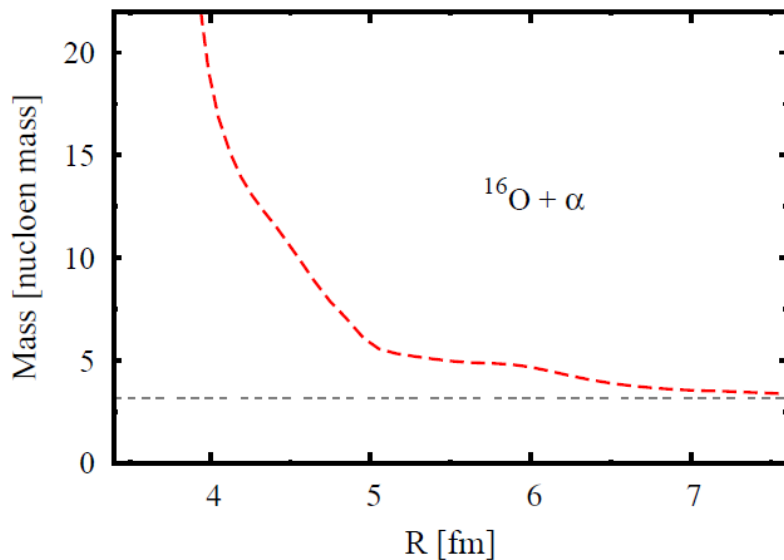
Inertial mass derived by ASCC method

Introducing the separation
plane at $z = z_s$:

$$\int_{z_s}^{+\infty} \rho(r) dr = M_{\text{pro}}$$

Definition of R :

$$\hat{R} \equiv z \left[\frac{\theta(z - z_s)}{M_{\text{pro}}} - \frac{\theta(z_s - z)}{M_{\text{tar}}} \right]$$



The reduced mass value can be well reproduced by ASCC method and Inglis cranking formula



Summary and Perspective

Thank you for your attention!

- ❑ *Based on the ASCC method, we extract the collective motion path for the system $\alpha+\alpha$, $^{12}\text{C}+\alpha$, $^{16}\text{O}+\alpha$, $^{16}\text{O}+^{16}\text{O}$,*
- ❑ *The self-consistent collective coordinate is found to be different from certain deformation parameters.*
- ❑ *The inertial mass parameters are calculated base on ASCC method.*

- ❑ *Our next plan:*
 - *To calculate the inertial mass for more heavier system.*
 - *Applying the more realistic nuclear interaction.*
 - *The mass parameter of other collective motion modes.*
 - *... ..*